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Estimating plot-level tree structure in a deciduous forest by combining allometric equations, spatial wavelet analysis and airborne LiDAR

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Object-oriented classification methods are increasingly used to derive plant-level structural information from high-resolution remotely sensed data from plant canopies. However, many automated, object-based classification approaches perform poorly in deciduous forests compared with coniferous forests. Here, we test the performance of the automated spatial wavelet analysis (SWA) algorithm for estimating plot-level canopy structure characteristics from a light detection and ranging (LiDAR) data set obtained from a northern mixed deciduous forest. Plot-level SWA-derived and co-located ground-based measurements of tree diameter at breast height (DBH) were linearly correlated when canopy cover was low (correlation coefficient ($r$) = 0.80) or moderate ($r$ = 0.68), but were statistically unrelated when canopy cover was high. SWA-estimated crown diameters were not significantly correlated with allometrically based estimates of crown diameter. Our results show that, when combined with allometric equations, SWA can be useful for estimating deciduous forest structure information from LiDAR in forests with low to moderate (<175% projected canopy area/ground area) levels of canopy cover.

1. Introduction

Plant canopy structure is a critical component of vegetated ecosystems because of its role in determining many ecosystem functions (Lefsky et al. 2002, Bohrer et al. 2009, Shugart et al. 2010, Hardiman et al. 2011). Many forest structure attributes can be obtained from relating allometric equations to height measurements and, therefore, efforts to remotely quantify spatially explicit canopy structure have been aided by advancements of three-dimensional light detection and ranging (LiDAR) techniques and the proliferation of LiDAR-derived data (e.g. Nelson et al. 1984, Dubayah and Drake 2000, Lefsky et al. 2002, Lim et al. 2003, van Leeuwen and Nieuwenhuis 2010, Yu et al. 2011). As the spatial resolutions of remotely sensed imagery and LiDAR have increased, so too have object-based approaches to data classification, which have facilitated the detection of individual vegetation objects (e.g. Falkowski et al.)
The combination of increasing spatial resolutions, availability of three-dimensional data sets and increasing focus on identification of individual vegetation objects have increased our ability to characterize detailed vegetation structure information at the ecosystem level and beyond.

The application of object-based classification algorithms for detecting and delineating trees in LiDAR data has been particularly successful in coniferous forests (e.g. Popescu and Wynne 2004, Falkowski et al. 2006, 2008, Koch et al. 2006, Yu et al. 2011). However, detecting trees within deciduous forests has proven to be more difficult (e.g. Popescu and Wynne 2004, Popescu et al. 2004, Anderson et al. 2006, Koch et al. 2006). This is likely because, within partly or fully closed deciduous canopies, there is a high level of crown overlap (Koch et al. 2006) and potentially because the tops of many deciduous crowns are relatively flat and irregularly shaped, making the detection of local maxima and crown boundaries difficult.

The objective of our study is to test the capability of spatial wavelet analysis (SWA) to detect deciduous trees within an airborne LiDAR data set. SWA has been used to identify conifer trees in LiDAR data with relatively high accuracy, even when stand density and canopy cover are very high (Falkowski et al. 2008), suggesting that it may be effective for detecting deciduous trees within continuous canopies. This is the first time that SWA has been tested for estimating tree structure information in a deciduous forest. We evaluate the performance of SWA by comparing LiDAR- and ground-based measurements using plot-level censuses and observed allometric relationships of plot-level deciduous tree structure. We also compare SWA results with the performance of TreeVaW (Kini and Popescu 2004), a software package that uses the variable filtering window method described by Popescu and Wynne (2004). The variable filtering window method has been reasonably successful for identifying tree- and plot-level deciduous forest structural characteristics using LiDAR data (Popescu et al. 2002, Popescu and Wynne 2004, Antonarakis et al. 2008), and thus provides a suitable method for comparison with SWA performance.

2. Materials and methods

2.1 Study area

This study was conducted in a northern mixed deciduous forest at the University of Michigan Biological Station (UMBS) located in the northern portion of Michigan’s lower peninsula (45° 33’35” N, 84° 42’49” W, 230 m elevation). Dominant land cover types within the study area include mixed forest and deciduous broadleaf forest. Overstorey tree species consists of (in the order of decreasing abundance) *Populus grandidentata* Michx. (bigtooth aspen), *Acer rubrum* L. (red maple), *Populus tremuloides* Michx. (quaking aspen), *Betula papyrifera* Marsh. (paper birch), *Quercus rubra* L. (red oak), *Fagus grandifolia* Ehrh. (American beech) and *Pinus strobes* L. (eastern white pine). The mean canopy height is roughly 18 m and the mean annual peak leaf area index (LAI) is approximately 3.8 m²/m². The mean stand density is 1012 stems/ha (281 stems/ha for trees with diameter at breast height (DBH) >20 cm).

2.2 Field survey

Measurements of DBH were acquired for all trees within sixty 16 m radius plots and one 60 m radius plot between June and August 2010. The 16 m radius plots were
arranged in seven transects radiating to the west (from 225° to 15°) from the 60 m radius plot at 20° intervals (Schmid et al. 2003). Along each transect, plots were located using 100 m spacing between plot centres. Allometric relationships relating DBH to height and crown diameter were calculated using observations from 112 trees (35 bigtooth aspen, 38 red maple and 39 eastern white pine) with DBH greater than 3 cm randomly sampled from within the 60 m radius plot (figure 1). Tree height was trigonometrically determined using the angle of inclination to tree stem apex, which was measured with a digital protractor (Mitutoyo, Aurora, IL, USA) located at a fixed distance from the tree stem. Crown diameter was determined by measuring, on the ground, the visually estimated greatest distance spanning the tree’s crown.

2.3 **LiDAR acquisition and processing**

LiDAR data were acquired in September 2009 for a 40 km² area of the UMBS forest. LiDAR acquisition was performed by the National Center for Airborne Laser Mapping (NCALM) using a Gemini ALTM© laser scanner (Optech Inc., West Henrietta, NY, USA) mounted on a fixed-wing aircraft flying at approximately 600 m above ground level. The sensor acquired data with a pulse rate frequency of 125 kHz and a scan frequency of 40 Hz. The data were collected in 35 flight lines with 366 m swath width and 50% overlap, producing an average point density of 9.5 points/m². Ground-based global positioning system (GPS) check points (n = 1023) that were collected during the flight were compared with the nearest neighbour LiDAR shot and returned an average difference of 0.05 m with SD of 0.07 m.

NCALM deliverables included a point cloud of laser returns and a digital elevation model (DEM) with 1 m spatial resolution created from ground returns. The point cloud was binned to the same grid as the DEM, and the highest return in each bin was registered. The field of highest returns was subtracted from the DEM to produce
the canopy height model (CHM). The CHM was further filtered so that canopy height values above the set minimum or maximum possible height (0 and 50 m) were replaced with the minimum or maximum value. There were less than 0.1% of the pixels that met this criterion. A $3 \times 3$ median filter was applied to the CHM to reduce within-crown height variability while still maintaining contrast at crown boundaries (Lillesand et al. 2004, Coggins et al. 2008). Figure 2(a) illustrates a subset of the resulting CHM within the UMBS forest.

### 2.4 Spatial wavelet analysis

The automated object-oriented SWA algorithm (Strand et al. 2006) was used to automatically detect the location and crown diameter of individual trees within the CHM (figure 2(a)). Similar to previous studies that used SWA for detecting vegetation objects in imagery (Strand et al. 2006, Garrity et al. 2008, Smith et al. 2008) and LiDAR (Falkowski et al. 2006, 2008), we used a two-dimensional Mexican hat wavelet mother function. SWA works by convolving a series of increasingly larger wavelets, each with an identical form as the mother function, with the CHM using a dilation scale ranging from 2 to 12 m and a step size of 0.25 m. SWA output consisted of the spatial coordinates ($x$, $y$) within the CHM of identified crown centre locations accompanied by the optimal dilation scale. The optimal dilation scale of each detected tree corresponds with the crown diameter and is identified by goodness-of-fit scores between wavelet dilation size and image object size (figure 2(b)). Additional details of the SWA algorithm are described by Falkowski et al. (2006) and Strand et al. (2006).

### 2.5 Data analysis

Geographic coordinates from the centre of each field survey plot were used to locate plots within the CHM. The CHM was split into sixty $30 \text{ m} \times 30 \text{ m}$ subsets and one $120 \text{ m} \times 120 \text{ m}$ subset, where each subset was geographically co-located with a plot. The SWA algorithm was applied to each subset to automatically detect the location of crown centres and crown diameters. At the location of each detected crown centre, height was obtained from the CHM and converted to DBH using the allometric relationship developed for the UMBS forest (see figure 1). The mean allometrically
derived DBH was calculated for each plot. Similarly, the TreeVaW software was used to automatically identify individual tree heights within the entire CHM. Subsets of the TreeVaW output were extracted from co-located plot areas. Mean plot-level DBH was allometrically calculated from the TreeVaW-estimated tree heights within each plot.

For each plot surveyed during the field campaign, the mean DBH from trees having a measured DBH greater than or equal to the 75th percentile was calculated. The 75th percentile was used in an effort to only include the top of canopy crowns for comparisons with SWA- and TreeVaW-detected trees because sub-canopy trees cannot be detected using a CHM. Mean crown diameter in each plot was obtained from the observed allometric equation (figure 1) using the measured DBH of canopy trees. Mean plot-level crown diameters were only compared with SWA-estimated diameters. TreeVaW uses a user-defined allometric equation to calculate crown diameter from each detected tree height, making comparison of performance for estimating DBH and crown diameter redundant.

Field-based canopy cover was calculated by dividing the sum of total crown area of each plot, which was allometrically calculated from field-measured DBH, by the ground area of each plot. The estimates of plot canopy cover were used to divide the plots into three canopy coverage classes: low (<125% cover), moderate (≥125% and <175% cover) and high (≥175% cover). Linear regression was used to evaluate the relationship between SWA- and field-derived means of plot DBH and crown diameter, and between TreeVaW- and field-derived means of DBH for all plots within each canopy cover class.

3. Results and discussion

Plot-level means of SWA-derived DBH and field-measured DBH were linearly correlated when all data were pooled (correlation coefficient \( r = 0.54 \), significance \( p < 0.01 \), root mean squared error (RMSE) = 3.35 cm). This relationship improved in areas where canopy cover was low \( (r = 0.80, p < 0.01, \text{RMSE} = 2.12 \text{ cm}) \) or moderate \( (r = 0.68, p < 0.01, \text{RMSE} = 2.79 \text{ cm}) \) (figure 3(a) and 3(b)). However, the relationship between SWA and field DBH was not statistically significant when canopy cover was high \( (r = 0.05, p = 0.86) \) (figure 3(c)). TreeVaW-derived DBH was not statistically correlated with field-measured DBH regardless of canopy cover class. SWA-estimated mean diameters were uncorrelated with DBH-based estimates of mean crown diameters (figure 3(d)–3(f)).

There were two areas where SWA performed poorly: estimating DBH in high canopy cover (>175%) and estimating crown diameter. Similar declines of SWA and other object-based performance have been reported in other ecosystems where canopy coverage is high (Strand et al. 2006, Falkowski et al. 2008, Garrity et al. 2008). In this study, decreased performance of SWA in high canopy cover conditions was likely due to crown overlap and prevalence of subdominant trees, which makes differentiation between trees difficult and increases the likelihood of omission or crown merging (Koch et al. 2006). Furthermore, SWA-based estimates of DBH relied on height information from LiDAR data so that any uncertainty in the CHM or in the allometric relationship between height and DBH would have decreased the goodness-of-fit in the correlation with field estimates.

Lack of significant correlation between SWA and field measures of crown size may have been, in part, due to the shape of the allometric relationships between DBH and crown diameter. SWA estimates crown diameter directly from the CHM, whereas
field-based estimates of crown diameter rely on the allometric relationship with DBH. Low sensitivity between crown diameter and DBH greater than approximately 10 cm (i.e. flatness of the crown diameter model in figure 1 above a DBH of 10 cm) leads to large uncertainty in crown diameter for large DBH observations. Lack of correlation between SWA and field crown diameters may have also been affected by crown shape. The Mexican hat wavelet function is used by the SWA algorithm to detect regularly shaped circular objects. Crown shape irregularities likely result in under- and over-estimation of crown size. Overall, these issues make it difficult to determine whether crown diameters from SWA or inferred from field measurements of DBH are more representative of the actual crown dimension.

4. Conclusions

Many potential applications will benefit from improved individual tree crown detection in broadleaf forests. Combined with allometric equations, remotely sensed tree structure information can supplement forest inventory data over large areas (e.g. Wulder et al. 2008) and provide data for dynamic vegetation, atmospheric or hydrodynamic models that resolve the ecosystem with a tree-level or sub-canopy level of representation for the vegetation (e.g. Bohrer et al. 2005, 2009, Medvigy et al. 2009), for large-scale estimates of standing biomass and carbon storage in forests (Asner et al. 2010) and for prediction of fuel properties and fire risks in hardwood forests (Skowronski et al. 2007). It can also provide data about the spatial statistics of the
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structure and tree distribution of forest patches, which can be used for the construction of virtual canopies for numerical studies of forest function (Bohrer et al. 2007).

Our results show that SWA performs relatively well for estimating tree structural information in deciduous forests relative to previous studies that used the image segmentation approach (e.g. Anderson et al. 2006, Koch et al. 2006) or the variable filter window approach tested in this study. Particularly in low to moderately dense plots, with up to 175% cover, SWA is a useful tool for extracting plot-level DBH information from LiDAR-derived tree heights. Although SWA-estimated crown diameters were not related to field measurements, future applications can leverage on allometric equations relating DBH to crown size and other structural information.

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References


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